

Communications Centre de recherches Research Centre sur les communications Canada Canada

An Agency of Industry Canada Un organisme d'Industrie Canada

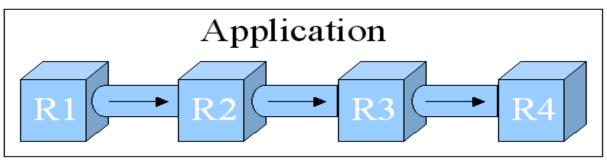
How Different Messaging Semantics Can Affect Applications Performances

Presented by: Steve Bernier, M.Sc., Research Manager Advanced Radio Systems Communications Research Centre Canada

Canadä



 SCA applications are made of several software components typically connected in a pipeline configuration



 Using the SCA, software components can be implemented by different organizations

- Interactions between components requires a middleware
- > The middleware for SCA is CORBA

This paper provides metrics comparing two types of CORBA interactions: One-way and Two-way

Using CORBA, every interaction is transformed into a message sent from a source component to a destination component

Two-way interactions

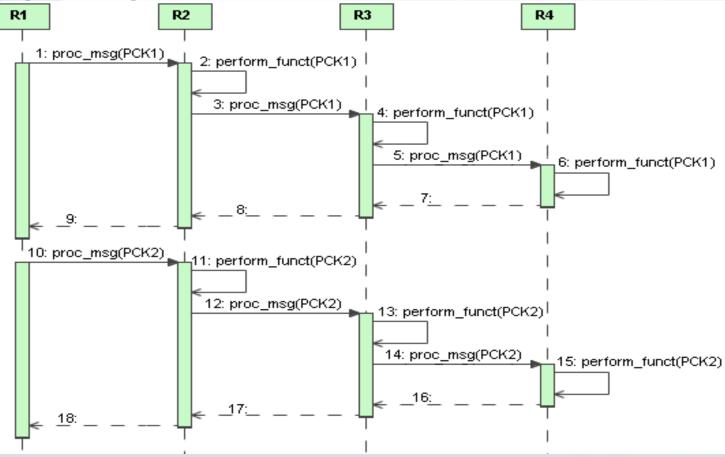
- Source is blocked until a response is received from the destination
- Synchronized with the target

One-way interactions

- Source is <u>not</u> blocked until a response is received from the destination
- > 3 levels of synchronization: with the middleware, with the transport, or with the server

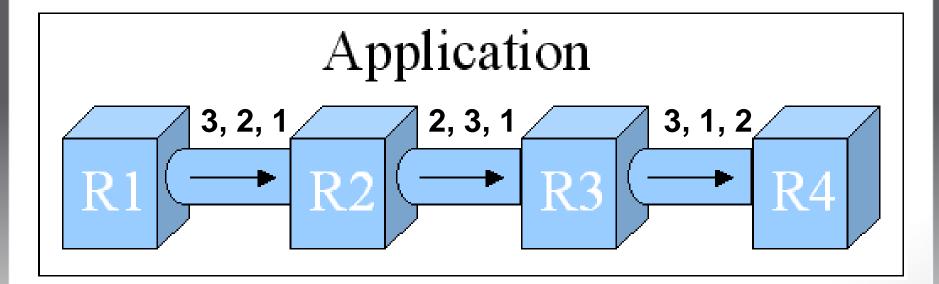
CDC

Two-way messaging can lead to the empty pipeline problem





One-way messaging can lead to the packet reordering problem



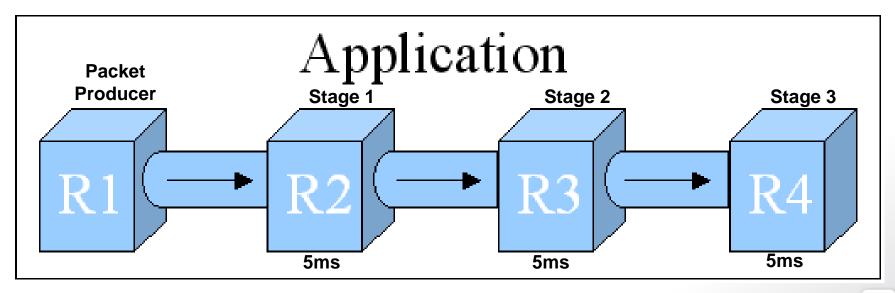
5

This paper provides metrics for 4 tests. All tests work as follows:

Pipeline configuration of 4 components

כסכ

- > The first component produces 1000 packets and sends them through a pipeline of 3 stages
- Each pipeline stage performs 5ms of work

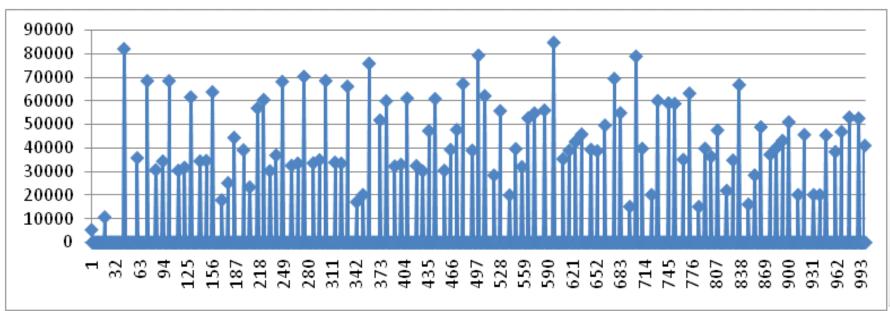


- One-way messaging, packet producer does not wait between each packet, synchronized with TCP/IP transport
- > Uses several threads in each pipeline stage
- Causes lots of packet reordering
- Should take less than 1000*5ms for all packets to go through the pipeline

	Stage 1	Stage 2	Stage 3
Time of last Pkt arrival	4463.20ms	4508.41ms	4513.61ms
# of Pkt reordered	315	520	612

- Time it took for the producer to send each packet to the transport
 - 10% of the packets in 44ms
 - 90% of the packets in 9usec

> Producer was paced by the transport



- One-way messaging, packet producer waits 5ms between each packet, synchronized with TCP/IP transport
- > Uses less threads in each pipeline stage
- Still causes some packet reordering
- Should take around 1000*5ms for all packets to go through the pipeline

	Stage 1	Stage 2	Stage 3
Time of last Pkt arrival	5416.57ms	5421.74ms	5426.90ms
# of Pkt reordered	95	216	349

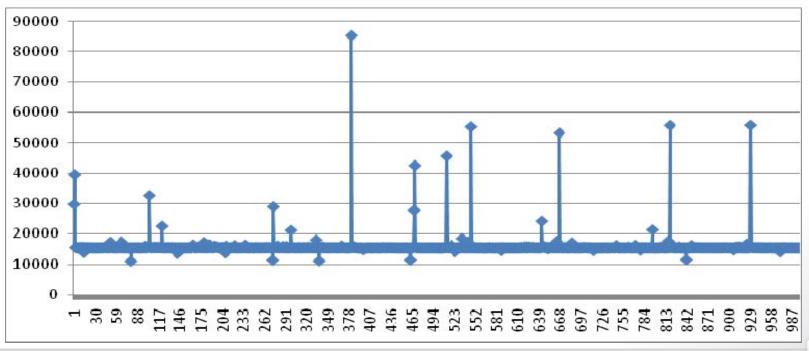
- > Two-way messaging, packet producer does not wait between each packet, synchronized with TCP/IP transport
- Causes the empty pipeline problem
- Should take at least 1000*5ms for each packet to go through each stage of the pipeline

	Stage 1	Stage 2	Stage 3
Time of last Pkt arrival	15,684.19ms	15,684.06ms	15,683.93ms
# of Pkt reordered	0	0	0

Test #3

CDC

- Time it took for the producer to send each packet to the transport
 - Average around 15ms with very few peeks



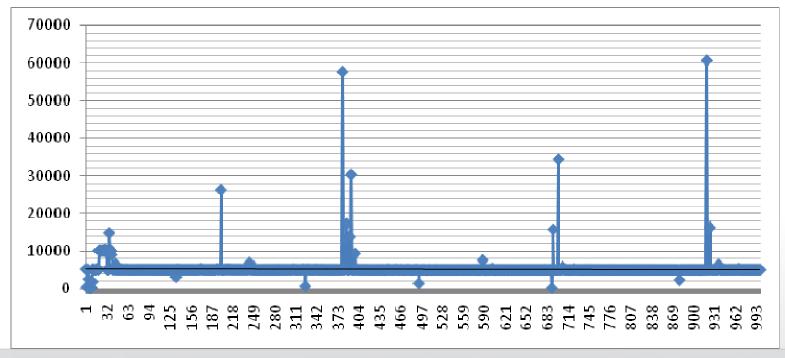
Producer was almost never paced by the transport

- Two-way messaging, packet producer does not wait between each packet, synchronized with TCP/IP transport
- Each stage uses one extra thread to decouple packet reception from packet transmission
- > Does not cause the empty pipeline problem
- Does not cause any packet reordering
- > Performance is better than using one-way messaging with a paced producer

	Stage 1	Stage 2	Stage 3
Time of last Pkt arrival	5286.22ms	5267.73ms	5297.16ms
# of Pkt reordered	0	0	0

* Test #4

- Time it took for the producer to send each packet to the transport
 - Average around 5ms with very few peeks
 - Producer was not paced by the transport as often



Conclusions

- One-way messaging does not necessarily offer better performances than two-way messaging
- > One-way messaging causes a large amount of packet reordering
 - not be suitable for most waveform applications
- > Two-way messaging naturally leads to the empty pipeline problem
- > Two-way messaging with an extra thread can yield interesting performances without packet reordering
 - Simple to use since flow control does not require explicit APIs

Questions?

COMMUNICATIONS RESEARCH CENTRE CANADA . CENTRE DE RECHERCHES SUR LES COMMUNICATIONS CANADA . WWW.CRC.CA

- 1998 Creates proprietary SDR architecture
- 2000 Implements FM radio for DnD using SCAv0.3
- 2001 Introduces the concept of Ports and Connections for SCAv1.0
- 2002 Releases Java™ open-source Reference Implementation (SCARI)
- * 2002 First demonstration of a commercial SCA waveform (DAB™)
- 2003 Introduces 1st commercial SCA development kit with modeling tools
- 2004 ReleasesSCARI2 open source, JTeL Certified (97.39%) SCAv2.2 CF
- 2004 Adds support for ORBexpress, INTEGRITY, and YellowDog Linux
- 2005 Introduces 1st SCA Xml validator and code generator
- 2006 Adds support for VxWorks 6.x
- 2007 Adds support for LynxOS
- 2007 Creates the world's smallest SCA FM radio
- 2008 Releases new generation Core Framework : SCARI-GT
- 2009 Adds support for TimeSys Linux
- 2010 Creates the first SCA virtual front panel

- 2000 Implemented a proof of concept SCA SDR for the Canadian Department of National Defence
 FM Line of sight application running on DSPs (TI C6201)
 - > Implemented a SCAv0.3 Core Framework
- - > Sponsored by the Software Defined Radio Forum
 - > Peer reviewed by a SDR Forum oversight committee:
 - MITRE JPO staff, US AFRL, L3-Communications, Mercury Computer Systems, Sun Microsystems, Space Coast Systems



- First demonstration of a commercial SCA SDR application
- Implemented in C++ and runs with SCARI

* 2003 – CRC releases its first commercial product called SCARI-Hybrid

> Java™/C++ SCA Core Framework with GUI tools

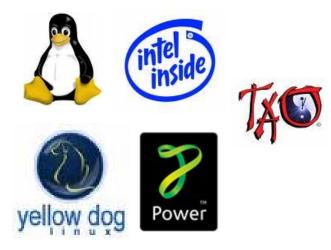
* 2004 - CRC selected by SDR Forum to develop a JTeL certified Core Framework

- Done in partnership with JTRS/JPO, JTRS/JTEL, NASA, Mercury Computers, Rohde and Schwarz, ISR Technology 19
- >Open source Java™ implementation of SCAv2.2
- Includes a one-channel push-to-talk FM application
- Demonstration performed at SDR'04 meeting
- Status: On-site certification process completed in only 5.5 days (2005, June 7-8-9-10, 14-15)
 - Meets 635 of the 652 SCA requirements for an unprecedented result of 97.39%



* 2004 – CRC's first fully embeddable Core Framework – SCARI++

- Implementation of the SCAv2.2 specification
- Support for Linux, Yellow Dog, and INTEGRITY
- Support for x86 and PPCs
- Support for CORBA: TAO and ORBexpress









* 2004 – First SDR platform using dynamic partial reconfiguration of an FPGA

- > Allow more than one application to "share" the FPGA
- Can switch applications without stopping the FPGA
- Platform developed by ISR Technologies in collaboration with Xilinx and CRC







* 2005 – Code Generation and XML validation

- > CRC was 1st to provide modeling tools in 2003
- CRC was also 1st to offer automated source code and XML generation from graphical models
- CRC also became 1st to offer reverse engineering and validation of SCA XML domain profiles
- > Latest version of the modeling tools is provided as an Eclipse[™] plug-in



2005 – Added support for more embedded SDR development kits

- > Added support for the Pentek 2510 SDR Kit
 - Complete software radio transceiver solution

* 2006 – Added support for more embedded operating systems and processors

> Added support for VxWorks and ARM processors

WIND RIVER **ARM**



2006 – Added support for the Lyrtech SFF SDR development kit

- Partnered with Lyrtech Signal Processing to offer support for the Small Form Factor (SFF) development kit
- > 1st platform to offer SCA integration ORB with DSP/FPGA
 - ORBexpress on DSP and on FPGA



* 2006 – Added support for the SDR4000 development kit

Partnered with Spectrum Signal Processing to offer support for the SDR4000 SCA SDR development kit



motherboards

2007 – Added support for more embedded operating systems and processors

> Added support for LynxOS and Marvell's PXA270 processor



* 2007 – Demonstration of the 1st SCA Radio using world's smallest computer

FM SCA Radio demonstration using a Gumstix









* 2007 – World's First High-Capacity Tactical Radio based on the SCA

- > AN/GRC-245A radio deployed by the US Army as part of the Increment-1 of WIN-T
- Since deployed by the Canadian Forces
- > Ultra has shipped close to 2000 units
- > Uses CRC's SCARI++ Core Framework





2008 – New Generation Core Framework SCARI-GT

- Results of 18 months or R&D
- Implements 6 optimization features for fast boots using small memory footprints

* 2009 – Core Framework for smaller form factors

> Adds support for TimeSys Linux on PPC





* 2010 – Adding support for new operating systems

- > Added support for Monta Vista Linux
- ➤ Adding support for Microsoft[™] Windows[™]
- > Adding support for QNX Neutrino



2010 – Created the first SCA Virtual Front Panel

- > Virtual Front Panel all controlled via SCA event channel and SCA PropertySet
- > Everything functional, LCD, Key Pad, and LEDs
- > Remote control HCLoS AN/GRC-245 radio from Ultra Electronics TCS





Communications Research Centre Overview

כיש



Performance

31

ר>< In Summary

CRC's recognized as a leader in the SCA community

- Has been leading for more than 10 years
- > Has a long list of industry firsts
- Influenced every version of the specification since SCAv0.3
- Is chairing the SDR Forum SCA Working Group
 - Working on an SCA interpretation guide
 - Working on APIs
- > CRC has the largest team of engineers dedicated to the SCA
 - CRC does not sale radios

ראכי In Summary

CRC's SCA technologies have been licenced to more than 40 organizations in 15 countries

- SCARI++ is the only COTS Core Framework to have been deployed in the battlefield
- > Customers in North-America, Europe, Middle-East, and Asia



- THE END -

COMMUNICATIONS RESEARCH CENTRE CANADA + CENTRE DE RECHERCHES SUR LES COMMUNICATIONS CANADA + WWW.CRC.CA